

Manual



COM461MT

BMS-Ethernet gateway for the connection
of Bender devices with BMS support
to Ethernet (TCP/IP)
using the Modbus/TCP protocol
Software version: D402 V1.0x



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6.2	Modbus requests	26
6.3	Modbus responses	26
6.4	Structure of the exception code	27
6.5	Modbus address structure for BMS devices	27
7.	Modbus process image in the memory of the COM461MT	29
7.1	Requesting data	29
7.1.1	Modbus function code	29
7.1.2	How are the memory areas organised?	29
7.2	Memory scheme of the process image	30
7.2.1	BMS device address assignment on the Modbus	30
7.2.2	Memory scheme of an individual BMS device	31
7.2.3	Device name	33
7.2.4	Timestamp	34
7.2.5	C = Common alarm and D = Device lost (device failure)	34
7.2.6	Channels 1 to 32 With analogue and/or digital values	35
7.2.6.1	Float = Floating point value of the BMS channels	35
7.2.6.2	A&T = Alarm type and test type (internal/external)	36
7.2.6.3	R&U = Range and unit	37
7.2.6.4	Channel description	39
7.2.6.5	Channel 33 to 64	40
7.3	Reference data records of the process image	41
7.3.1	Address assignment of the reference data record	41
7.3.2	Reference value on channel 1	42
7.3.3	Reference value on channel 2	43
7.3.4	Explanation of how to access floating point values	43
7.4	Channel descriptions for the process image	45
7.5	Modbus control commands	57
8.	Technical data	59
8.1	Tabular data	59
8.2	Dimension diagram	61
8.3	Standards, approvals, certifications	61

8.4	Ordering data	62
9.	Troubleshooting	63
9.1	Damage in transit	63
9.2	Malfunctions	63
9.2.1	What should be checked?	63
9.2.2	Where do you go to get help?	64
INDEX	65

1. Making effective use of this document

1.1 How to use this manual

This operating manual is aimed at qualified experts in electrical engineering and communications technology!

To make it easier for you to understand and revisit certain sections of text and instructions in the manual, we have used symbols to identify important instructions and information. The meaning of these symbols is explained below:



Information calling attention to hazards are marked with this warning symbol.



Information intended to assist the user to make optimum use of the product are marked with the Info symbol.

1.2 Overview of chapters

- Making effective use of this document:
This chapter gives you instructions on how to use this documentation
- Safety instructions:
This chapter describes the dangers during installation and when operating the device
- Product description:
This chapter describes the scope of delivery and features of the product

- **Installation, connection and commissioning:**
This chapter shows the steps to take up to commissioning
- **The BMS-Ethernet gateway COM461MT:**
This chapter describes the display and operating elements
- **Data access using Modbus/TCP protocol:**
Describes how to send requests to the Modbus/TCP server in the COM461MT and how the responses are to be interpreted
- **Modbus process image in the COM461MT's memory:**
In this chapter, the representation of BMS data on Modbus/TCP structures is described in detail
- **Technical data:**
In addition to the technical data you will find here ordering data
- **Troubleshooting:**
This chapter offers service and support in case of malfunction. In addition you will also find here information on our Technical Service department
- **Index:**
The key word index assists you in finding the term you are searching for.

1.3 Quick reference guide

Connection of the COM461MT

If you are familiar with the installation and connection of electrical devices as well as networking, particularly with Ethernet, you can start right away with the wiring diagram on page 17.

It may also be helpful to refer to block diagrams representing an application example with an internal bus on page 14.

Using the Modbus/TCP functions

Information about this complex field can be found from page 25.

2. Safety instructions

2.1 Work activities on electrical installations

- Only skilled persons are permitted to carry out the work necessary to install, commission and run a device or system.
- Compliance with applicable regulations governing work on electrical installations, and with the regulations derived from and associated with them, is mandatory. EN 50110 is of particular importance in this regard.



Any work on electrical installations which is not carried out properly can lead to death and injury!

- If the device is being used in a location outside the Federal Republic of Germany, the applicable local standards and regulations must be complied with. European standard EN 50110 can be used as a guide.

2.2 Intended use

The BMS-Ethernet gateway COM461MT connects the serial BMS bus to Ethernet TCP/IP networks. The gateway converts alarms, measured values and statuses from the BMS bus to the Modbus/TCP protocol. This allows connection to Modbus networks.

The gateway is operated on the **internal** BMS bus.

2.3 Address setting and termination

In order to ensure proper functioning of the BMS-Ethernet gateway COM461MT, correct address assignment and termination of the BMS bus is of utmost importance.



Assigning addresses that are already used by existing devices in the BMS or TCP/IP networks concerned may cause serious malfunctions.

Ensure correct address setting and termination of the COM461MT.
For details refer to the chapter basic configuration from page 19.

2.4 Protection against unauthorized access



Risk of damage to equipment due to unauthorized access.

Attackers from the Internet may be able to read data and to change settings.

It is absolutely necessary to ensure that

- the network is separated from the Internet*
 - common security mechanisms are applied (firewall, VPN access)*
-

3. Product description

3.1 Scope of supply

You will receive:

- the COM461MT
- an operating manual

3.2 A short description

The BMS-Ethernet gateway COM461MT contains a Modbus/TCP server that converts the BMS data for a Modbus client.

A web server makes it possible to configure the COM461MT (see “Commissioning” on page 19).

Ethernet-TCP/IP interface:

The coupling is performed via the internal Layer-2 switch. Two Ethernet ports are available.

Interface on the BMS side:

COM461MT can be operated as a master or slave.

3.3 Properties

- Setting of the IP address, BMS address and time/date using standard web browser
- Time synchronisation for all BMS bus devices
- Integrated Ethernet switch: 2 x RJ45, 10/100 Mbit/s
- Operation on the internal BMS bus
- Modbus/TCP data access to the internal BMS bus, max. 150 BMS devices
- Commands can be sent from an external application (e.g. data display software) to BMS devices and measured values read.

3.4 Possible applications

- Usage of professional data display programs by converting the BMS data to the Modbus/TCP protocol
- Observing and analysing Bender products that support communication, such as RCMS, EDS and MEDICS® systems

4. Installation, connection and commissioning

The BMS-Ethernet gateway is normally integrated into existing LAN structures, but can also be operated via a single PC on the Ethernet side.



*If you are familiar with the configuration of computer networks, you can carry out the connection of the COM461MT yourself. **Otherwise please contact your EDP administrator!***

4.1 Preliminary considerations

1. Have all the questions as regards the installation been answered by the technician responsible for the installation?
2. The device is operated on the internal BMS bus. Is the BMS address to be set known?

If, apart from the COM461MT, an alarm indicator and test combination MK800 is connected to the internal bus, the COM461MT must **not** have the address 1 (master).

You will find more detailed information on the BMS topic, in particular about the wiring of bus devices, in the separate document "BMS bus". You can download the document from the download area of the website www.bender-de.com.

3. Request network data from the technician responsible for the installation. The IP address and subnet mask are to be set manually.
4. Ask for the IP address of the NTP server, which is required for automatic time setting.
5. Are suitable PC hardware and software available for commissioning? - Minimum system requirements: 1.6-GHz processor/512 MB RAM / Windows XP/Vista/7/Web browser.

For initial connection, the basic configuration of the COM461MT is to be undertaken outside the installation, depending on the specific situation.

4.2 COM461MT on the internal BMS bus

Bender systems such as EDS46x/49x, RCMS46x/49x and MEDICS communicate with each other via the Bender measuring device interface BMS. The BMS-Ethernet gateway COM461MT provides the coupling between the BMS bus and TCP/IP networks. The internal Modbus/TCP server in the COM461MT communicates with the Modbus/TCP client via these networks. The following block diagram illustrates the operation of the gateway on the internal BMS bus.



Internal and external BMS bus

The majority of Bender devices communicate via the internal BMS bus.

Individual devices, such as MK800, TM 800 or Bender panels can communicate via both the internal BMS bus (BMS i) and the external BMS bus (BMS e).

The BMS-Ethernet gateway COM461MT can only communicate via the internal BMS bus (BMS i).

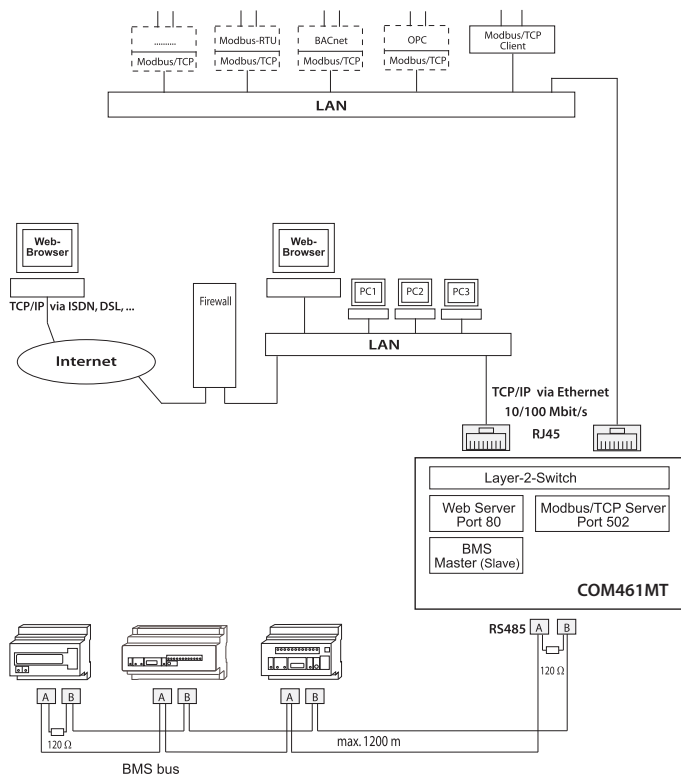


Fig. 4.1: Block diagram of a coupling between an **internal** BMS bus and TCP/IP networks

4.3 Installing the device

Possible methods of mounting:

- DIN rail mounting
- Screw mounting with 2 x M4 (dimension diagram on page 61)



When installing the device, please take into consideration that the device is only to be used in locations that are protected from unauthorised entry!

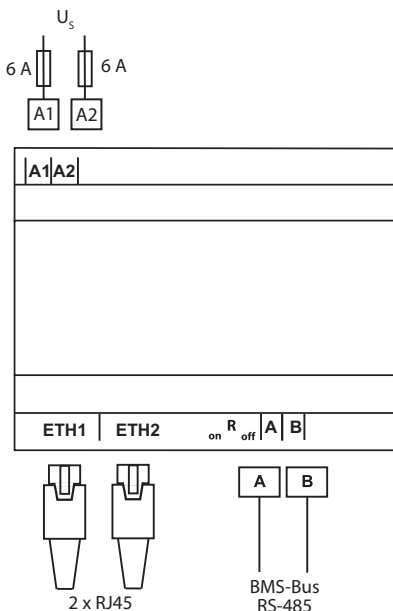
This can be installation in a switch cabinet, for example.

4.4 Connecting the device

For UL applications, the following is to be observed:

- Supply voltage U_s see nameplate and ordering data
- Maximum ambient temperature 55°C
- For use in pollution degree 2 environments
- Only 60/75 °C copper wires are to be used
- Tightening torque for terminals 0.5...0.6 Nm

Connect the terminals and sockets on the COM461MT according to the wiring diagram.



Terminal	Description
A1, A2	Connection to the supply voltage, 6 A fuse recommended, two-pole fuses should be used on IT systems. For UL and CSA applications, it is mandatory to use 5 A fuses
ETH1, ETH2	Two connections for connection to a personal computer or to the local network (hub, switch, router); Connection using a CAT5 cable; internal Layer-2 switch with cable autodetect.
A, B	Connection to the internal BMS bus with shielded cable (e.g. J-Y(St)Y 2x0.8)
R _{on/off} (A,B)	Switch for BMS bus termination. When the device is installed at the end of the bus, set the terminating switch to "on".

4.5 Commissioning

1. Apply the supply voltage to the COM461MT. The green "ON" LED illuminates.
2. Connect the COM461MT to a PC and open a web browser.
3. Enter the IP address for the COM461MT (factory setting 192.168.0.254). The page for the device settings appears:

Settings

IP address	<input type="text" value="172.16.60.64"/>
Subnet	<input type="text" value="255.255.0.0"/>
Bms address	<input type="text" value="2"/>
Modbus control	<input type="text" value="Off"/> ▼
Ntp active	<input type="text" value="Off"/> ▼
Ntp-Server address	<input type="text" value="192.168.0.123"/>
UTC	<input type="text" value="+1"/> ▼
Summertime	<input type="text" value="Off"/> ▼
Date	<input type="text" value="12/11/2012"/> mm/dd/yyyy
Time	<input type="text" value="10:17"/> hh:mm <input checked="" type="checkbox"/> skip time

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Without address data it is not possible to access the device.

If the IP address and subnet mask are not known, this information can only be found with a large amount of effort (see "Determining address data" on page 22).

If the factory settings are changed, **always** note the modified address data in the following table.

4. Make the necessary settings. Make a note of the modified settings:

Parameter	Meaning	Factory setting	Modified setting
IP address	IP address of the COM461MT	192.168.0.254	
Subnet	Subnet mask of the COM461MT	255.255.0.0	
Bms address	Address on the internal BMS bus	2	
Modbus control	Enable or disable control via Modbus	On	
Ntp-Server address	IP address of the NTP server, is required for automatically setting the time	192.168.0.123	
UTC	Time zones setting (-12...+13): UTC + 1 h = CET UTC + 2 h = ... UTC + 3 h = ...	+1	

Parameter	Meaning	Factory setting	Modified setting
Summer-time	Select summer time setting: Off = Function disabled DST = Automatic switchover, USA, CDN CEST = Automat. switchover, Central Europe On = Set time zone + 1 h	Off	
Date	Date		
Time	Time of day		
skip time	Skip time setting. The time remains unchanged.	<input checked="" type="checkbox"/>	

- Click "Change" to save the modified settings. Or click "Undo" to undo the changes made.

4.5.1 Determining address data

The IP address and subnet mask set must be known for the operation of the COM461MT. If these data have been changed without making a note of the modified address data, the following options are available:

- Enter NetBIOS name in the web browser: "http://com461mt" or "com461mt" (dependent on the browser). Requirement: COM461MT and PC must lie in the same address range.
- Connect a COM460IP with option C to the network. Set address data again using COM460IP.
- Connect a COM460IP with option A to the network. Read address data using COM460IP.
- Install an IP scanner on a PC in the network and find address.
- Have COM461MT reset to the factory setting by Bender.

5. The BMS-Ethernet gateway COM461MT

5.1 Display and operating elements

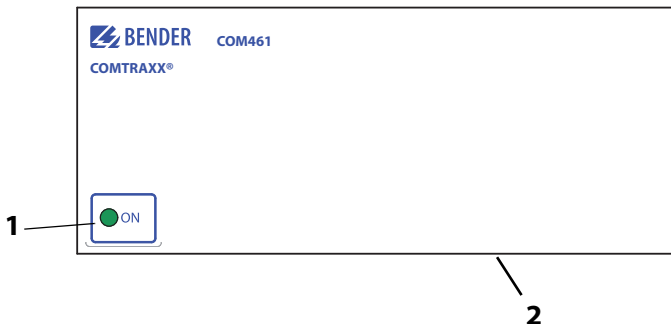


Fig. 5.1: COM461MT front panel

Key

- 1 "ON" LED lights when supply voltage is applied
- 2 Ron/off (beside terminals A, B)
Switch for terminating the BMS bus. When the device is installed at the end of the bus, set the terminating switch to "on".

6. Data access using Modbus/TCP protocol

Requests are sent to the Modbus/TCP server in the COM461MT using function code FC4 (read input register). The server generates a function-related response and sends it to the Modbus client.

6.1 Exception code

If a request cannot be answered for whatever reason, the server sends a so-called exception code with which possible faults can be narrowed down.

Exception code	Description
0x01	Impermissible function
0x02	Impermissible data access
0x03	Impermissible data value
0x04	Slave device error
0x05	Acknowledgement of receipt (response delayed)
0x06	Request not accepted (repeat request, if necessary)
0x08	Memory: parity error
0x0A	Gateway path not available
0x0B	Gateway error

6.2 Modbus requests

The required words of the process image can be read from the input registers in the COM461MT using the function code FC4. For this purpose, the start address and the number of registers to be read need to be entered.

Example:

The words 0 and 1 are to be read from the input registers 0x100 and 0x101.

Byte	Name	Example
Byte 0, 1	Transaction identifier	0x0000
Byte 2, 3	Protocol identifier	0x0000
Byte 4, 5	Length field	0x0006
Byte 6	Unit identifier	0x01
Byte 7	MODBUS function code	0x04
Byte 8, 9	Device address (BMS int * 0x100)	0x0100 (corresponds to the internal BMS address 1), internal BMS bus address assignment
Byte 10, 11	Number of words	0x0002

6.3 Modbus responses

The responses consist of 2 bytes per register. The MSB is the first byte.

Byte	Name	Example
...
Byte 7	MODBUS function code	0x04
Byte 8	Byte count	0x04

Byte	Name	Example
Byte 9, 10	Value register 0	0x1234 (fictitious value)
Byte 11, 12	Value register 1	0x2345 (fictitious value)

6.4 Structure of the exception code

Byte	Name	Example
...
Byte 7	MODBUS function code	0x84
Byte 8	Exception code	0x01 or 0x02

6.5 Modbus address structure for BMS devices

Function	Address range	Number of bytes	Number of words
Device name	0x00...0x09	20 bytes	10 words
Timestamp	0x0A...0x0D	8 bytes	4 words
Common alarm	0x0E (high byte)	1 byte	0.5 words
No BMS bus connection	0x0E (low byte)	1 byte	0.5 words
Not used	0x0F	2 bytes	1 word
Channel 1...32	0x10...0x8F	32 x 8 bytes	128 words
Alarm and test Channel 33...64	0x90...0xFC	218 x 8 bytes	109 words

7. Modbus process image in the memory of the COM461MT

The device holds a process image in the memory. This image represents the current statuses and values of up to 150 BMS devices for each monitored internal BMS bus.

7.1 Requesting data

7.1.1 Modbus function code

The memory in the COM461MT can be read using the Modbus function 4 "Read input registers". The volume of the data requested depends on the number of bytes selected in the Modbus client used. Up to 125 words (0x7D) can be read with a single request. An individual addressable byte, such as the set bit for a stored common alarm, can also be read.

7.1.2 How are the memory areas organised?

Memory utilisation	Start address	End of memory area	Size of memory area
Reference values for test purposes	0x0000	0x00FF	0x0100
Process image	0x0100	0x95FF	0x9500
Not used	0x96FF	0xFFFF	0x6900



For some Modbus clients an offset of 1 must be added to the register addresses. Example: process image start address = 0x0101.

The assignment of the memory addresses and the associated memory content is described below.

7.2 Memory scheme of the process image

7.2.1 BMS device address assignment on the Modbus

As illustrated in the table, the Modbus start address for the respective process image is derived from the BMS device address. 256 (0x100) words or 512 bytes are reserved for each BMS device. They contain all the information requested and transmitted from the BMS bus.

Modbus address ranges of the process images in the memory				
BMS device address	Word			
	HiByte	LoByte		
		00	...	FF
1	0x01	Device 1		
2	0x02	Device 2		
3	0x03	Device 3		
...		
32	0x20	Device 32		
...		
150	0x96	Device 150		

Tab. 7.1: Modbus start address for each BMS device for which a request can be sent.

7.2.2 Memory scheme of an individual BMS device

BMS devices can feature various types of analogue and/or digital channels. Please take into consideration that there are device-specific differences:

- BMS devices usually feature 12 channels
- MK800/TM800 supports up to 64 digital channels in the master mode
- The channels 33 to 64 transmit digital messages only

Use the tables on page 30 and page 33 to determine the start address to request the following device parameters:

- Device name
- Timestamp
- Common alarm
- Device error
- BMS channel

Example:

In our example, data is to be requested from channel 2 of the device with BMS address 3. How is the start address determined to send the request for the channel? In our example, the relevant cells in the table are marked bold.

1. For BMS device address 3 the first part of the address, 0x03 (high byte), is taken from Table 7.1.
2. For channel 2 the second part of the address, 0x14 (low byte), is taken from Table 7.2. For the number of words to be requested the number 4 is taken from the same table: (0x14 to 0x17 = 0x04).
3. The start address 0x0314 is formed from the high byte and low byte.

Memory image of a BMS device																																		
LoByte	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F																		
0x00	----- Device type -----										--- Timestamp ---			C	D	R.																		
0x10	Channel 1				Channel 2				Channel 3				Channel 4																					
0x20	Channel 5				Channel 6				Channel 7				Channel 8																					
0x30	Channel 9				Channel 10				Channel 11				Channel 12																					
0x40	Channel 13				Channel 14				Channel 15				Channel 16																					
0x50	Channel 17				Channel 18				Channel 19				Channel 20																					
0x60	Channel 21				Channel 22				Channel 23				Channel 24																					
0x70	Channel 25				Channel 26				Channel 27				Channel 28																					
0x80	Channel 29				Channel 30				Channel 31				Channel 32																					
0x90	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64		
0xA0	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.
0xB0	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.
0xC0	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.

0xD0	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.
0xE0	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.
0xF0	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.	R.

Tab. 7.2: Modbus address assignment of the channels in a BMS device;
Hex representation: horizontal = units , vertical = sixteens

Abbreviations for memory contents:

C = Common alarm

D = Device lost (device failure)

R. = Reserved

A detailed description of the data formats for the device name, timestamp etc. is given below.

7.2.3 Device name

Word 0x00	0x01	0x02	0x03	0x04	0x05	0x06	0x07	0x08	0x09
ASCII text, 10 words/20 bytes									

The device name is set using a BMS bus scan.

7.2.4 Timestamp

Word 0x0A		0x0B		0x0C		0x0D	
HiByte	LoByte	HiByte	LoByte	HiByte	LoByte	HiByte	LoByte
Year YY		Month MM	Day DD	Hour hh	Minute mm	Second ss	Re- served

The timestamp is set according to a datagram received from a transmitting device.

7.2.5 C = Common alarm and D = Device lost (device failure)

Word 0x0E	
HiByte	LoByte
C	D
Common alarm, 1 byte: LSB = 0 or 1	Device error, 1 byte: LSB = 0 or 1

The common alarm bit is set as soon as an alarm status from the respective BMS device is detected.

The device error bit is set when communication with the respective BMS device is no longer possible.

7.2.6 Channels 1 to 32 With analogue and/or digital values

Word 0x00		0x01		0x02		0x03	
HiByte	LoByte	HiByte	LoByte	HiByte	LoByte	HiByte	LoByte
Floating point value (Float)				AT&T	R&U	Channel description	

Every analogue BMS device channel can contain alarm messages, operating messages, measured values, test messages and descriptive text. Both analogue and digital information can be transmitted.

AT&T = Alarm type and test type (internal/external)

R&U = Range and unit

For details on the channel description refer to chapter 7.4.

7.2.6.1 Float = Floating point value of the BMS channels

Bit	Word 0x00																Word 0x01															
	HiByte								LoByte								HiByte								LoByte							
	31	30						24	23	22					16	15	8	7									0					
	S	E	E	E	E	E	E	E	E	M	M	M	M	M	M	M	M	M	M	M	M	M	M	M	M	M	M					

Representation of the bit order for processing analogue measured values according to IEEE 754

S = Sign

E = Exponent

M = Mantissa

